## ACME SCREW LINEAR ACTUATOR ATL 10 AC motor

OVERALL DIMENSIONS
La =Lc + Stroke
Stroke
Length
Standard head
with threaded
hollow bore


## ACME SCREW LINEAR ACTUATOR ATL 10 AC motor

## PERFORMANCES AND FEATURES

- Push load up to 5000 N
- Pull load up to 4000 N
- Linear speed up to $140 \mathrm{~mm} / \mathrm{s}$
- Standard stroke lengths: 100, 150, 200, 300, 400, 500 mm (for different / longer stroke lengths please contact us)
- Aluminium alloy housing and rear attachment, with bronze bush
- Anodized aluminium outer tube
- Chrome-plated steel push rod - tolerance f7
- Standard head BA or rod end ROE in stainless steel AISI 303 with bronze bush
- AC 3-phase or 1-phase motor (motor features details on page 70)
- Duty cycle with max load: $30 \%$ over 10 min at $(-10 \ldots+40)^{\circ} \mathrm{C}$
- Standard protection IP55 (IP54 with brake)
- Standard motor mounting position as per sketch (right-hand, code RH)
- Long-life lubrication, maintenance free


## ACCESSORIES

- Different front attachments
- Stainless steel push rod (code SS)
- Rear bracket (code SP)
- Mechanical overload protection, safety clutch (code FS)
- Brake motor
- Two adjustable stroke end reed switches (code FCM)
- Extra switches for intermediate positions
- Electromechanical stroke end switch for linear speed up to $30 \mathrm{~mm} / \mathrm{s}$ (code FCE) (technical data on page 72)


## OPTIONS

- Motor mounting position on opposite side (left-hand, code LH)
- Fixing attachment turned at $90^{\circ}$ (code RPT 90)

PERFORMANCES with AC 3-phase $50 \mathrm{~Hz} 230 / 400$ V or 1-phase 50 Hz 230 V motor

| 1-start acme screw $\operatorname{Tr} 14 \times 4$ |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| RATIO | $0.09 \mathrm{~kW}-\mathbf{4}$ pole motor | 0.12 kW - 2 pole motor |  |  |
|  | LOAD $[\mathrm{N}]$ | SPEED $[\mathrm{mm} / \mathrm{s}]$ | LOAD $[\mathrm{N}]$ | SPEED $[\mathrm{mm} / \mathrm{s}]$ |
| RH1 | 1750 | 23 | 1250 | 47 |
| RV1 | 2620 | 15 | 1860 | 30 |
| RN1 | 4490 | 7.5 | 3230 | 15 |
| RL1 | 5000 | 3.5 | 5000 | 7.5 |
| RXL1 | 5000 | 2 | 5000 | 3.5 |


| 2-starts acme screw $\operatorname{Tr} 14 \times 8(\mathrm{P} 4)$ |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| RATIO | $0.09 \mathrm{~kW}-4$ pole motor | 0.12 kW - 2 pole motor |  |  |
|  | LOAD $[\mathrm{N}]$ | SPEED $[\mathrm{mm} / \mathrm{s}]$ | LOAD $[\mathrm{N}]$ | SPEED $[\mathrm{mm} / \mathrm{s}]$ |
| RH2 | 1070 | 47 | 790 | 93 |
| RV2 | 1620 | 30 | 1180 | 60 |
| RN2 | 2880 | 15 | 2080 | 30 |
| RL2 | 4800 | 7.5 | 3520 | 15 |


| 3-starts acme screw $\operatorname{Tr} 14 \times 12(\mathrm{P} 4)$ |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| RATIO | $0.09 \mathrm{~kW}-\mathbf{4}$ pole motor | 0.12 kW - 2 pole motor |  |  |
|  | LOAD $[\mathrm{N}]$ | SPEED $[\mathrm{mm} / \mathrm{s}]$ | LOAD $[\mathrm{N}]$ | SPEED $[\mathrm{mm} / \mathrm{s}]$ |
| RH3 | 800 | 70 | 560 | 140 |
| RV3 | 1210 | 45 | 860 | 90 |
| RN3 | 2190 | 22 | 1540 | 45 |
| RL3 | 3680 | 11 | 2680 | 22 |

## Self-locking conditions

Information about statically self-locking conditions with pull or push load on page 68.
ORDERING CODE EXAMPLE

| ATL 10 | RL1 | C200 | CA 230/400 V | FCM |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Actuator | Selected <br> ratio | Required <br> stroke | Motor | Stroke end <br> switches | Accessories | Options |  |  |

## ACME SCREW LINEAR ACTUATOR ATL 10 DC motor

OVERALL DIMENSIONS


| STROKE CODE | C100 | C150 | C200 | C300 | C400 | C500 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Working stroke length with FCE $[\mathrm{mm}]$ | 100 | 150 | 200 | 300 | 400 | 500 |
| Working stroke length with FCM $[\mathrm{mm}]$ | 73 | 123 | 173 | 273 | 373 | 473 |



## ACME SCREW LINEAR ACTUATOR ATL 10 DC motor

## PERFORMANCES AND FEATURES

- Pull-Push load up to 4000 N
- Linear speed up to $150 \mathrm{~mm} / \mathrm{s}$
- Standard stroke lengths: $100,150,200,300,400,500 \mathrm{~mm}$ (for different / longer stroke lengths please contact us)
- Aluminium alloy housing and rear attachment, with bronze bush
- Anodized aluminium outer tube
- Chrome-plated steel push rod - tolerance f7
- Standard head BA or rod end ROE in stainless steel AISI 303 with bronze bush
- DC 12 or 24 V motor (motor features details on page 69)
- Duty cycle with max load:
$30 \%$ over 10 min at $(-10 \ldots+40)^{\circ} \mathrm{C}$
- Standard protection IP54
- Standard motor mounting position as per sketch (right-hand, code RH)
- Long-life lubrication, maintenance free


## ACCESSORIES

- Different front attachments
- Stainless steel push rod (code SS)
- Rear bracket (code SP)
- Mechanical overload protection: safety clutch (code FS)
- Brakemotor
- Bi-directional incremental encoder, 100 ppr with zero set pulse, Push-Pull, $8 \div 24$ Vdc (code EH38)
- Two adjustable stroke end reed switches (code FCM)
- Extra switches for intermediate positions
- Electromechanical stroke end switch for linear speed up to $30 \mathrm{~mm} / \mathrm{s}$ (code FCE) (technical data on page 72)


## OPTIONS

- Motor mounting position on opposite side (left-hand, code LH)
- Fixing attachment turned at $90^{\circ}$ (code RPT 90)

PERFORMANCES with 24 V DC motor
(Performances with 12 V DC motor: same load, linear speed $10 \%$ less, electrical consumption 2 times more)

| 1-start acme screw $\operatorname{Tr} 14 \times 4$ |  |  |  |
| :---: | :---: | :---: | :---: |
| RATIO | LOAD $[\mathrm{N}]$ | SPEED $[\mathrm{mm} / \mathrm{s}]$ | CURRENT [A] |
| RH1 | 680 | 50 | 4 |
| RV1 | 1020 | 32 | 4 |
| RN1 | 1770 | 16 | 4 |
| RL1 | 2960 | 8 | 4 |
| RXL1 | 4000 | 4 | 4 |


| 2-starts acme screw $\operatorname{Tr} 14 \times 8(\mathrm{P} 4)$ |  |  |  |
| :---: | :---: | :---: | :---: |
| RATIO | LOAD $[\mathrm{N}]$ | SPEED $[\mathrm{mm} / \mathrm{s}]$ | CURRENT [A] |
| RH2 | 430 | 100 | 4 |
| RV2 | 650 | 64 | 4 |
| RN2 | 1160 | 32 | 4 |
| RL2 | 1970 | 16 | 4 |


| 3-starts acme screw $\operatorname{Tr} 14 \times 12(\mathrm{P} 4)$ |  |  |  |
| :---: | :---: | :---: | :---: |
| RATIO | LOAD $[\mathrm{N}]$ | SPEED $[\mathrm{mm} / \mathrm{s}]$ | CURRENT [A] |
| RH3 | 310 | 150 | 4 |
| RV3 | 470 | 96 | 4 |
| RN3 | 840 | 48 | 4 |
| RL3 | 1430 | 24 | 4 |

## Self-locking conditions

Information about statically self-locking conditions with pull or push load on page 68.
ORDERING CODE EXAMPLE

| ATL 10 | RL1 | C200 | CC 24 V | FCM |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Actuator | Selected <br> ratio | Required <br> stroke | Motor | Stroke end <br> switches | Accessories | Options |  |

## 13. STROKE END SWITCHES AND POSITIONING CONTROL

## GENERAL NOTE

In case the linear actuator is used in an application where the stroke end switches must be connected to PLC or PC, we suggest to make the connection with a galvanic separation circuit.

13.1 Magnetic stroke end switches (reed) FCM (linear actuators ATL, BSA, UAL, UBA Series, LMI 02 and LMP 03)


The magnetic field of the ring fixed on the nut activates the reed contact of the switch locked on the protective tube with a clamp.
The position of the switches along the tube is easily adjustable.
The switches used to determine any intermediate position (between Lc and La) will switch over in two different positions, depending on the push rod motion direction (extending or retracting).
WARNING! The magnetic reed-switches can work only if connected to a wiring control circuit in order to activate the electric relay. Do not connect them in series between the power supply and the electric motor!

| REED CONTACT RATED VALUE |  |  |
| :--- | :---: | :---: |
|  | DC | AC |
| Rated voltage | $(3 \ldots 130) \mathrm{V}$ | $(3 \ldots 130) \mathrm{V}$ |
| Max. commutable power | 20 W | 20 VA |
| Max. commutable current | 300 mA (resistive load) |  |
| Max. inductive load | 3 W |  |

Standard: NC switch (normally closed contact)
equipped with signalling LEDS and protective
varistor against voltage peaks.
Standard cable length 2 m ; wires $2 \times 0.75 \mathrm{~mm}^{2}$
Different configurations available on request:
NO (normally open); CS (exchanging contact).
For more information please contact our Technical Dpt.

### 13.2 Electric stroke end switches FCE (actuators ATL 10, ATL 12, BSA 10, BSA 12)



| CONTACT RATED VALUE |  |  |
| :---: | :---: | :---: |
| Voltage | Mesistive load current | Inductive load |
| 250 Vac | 5 A | 3 A |
| 30 Vdc | 5 A | 0.1 A |
| 125 Vdc | 1.4 A | - | are activated by two adjustable rings through a shaft collar. Standard switches are wired on the NC contact, cable length 1.5 m ; wires $4 \times 0.75 \mathrm{~mm}^{2}$

On request, they can be wired on the NO contact or on the switch-over contact CS (for available configurations please contact our Technical Dpt).
Min retracted length Lc is adjusted by ring 1. FC1 switch is connected with the WHITE and the BROWN cables.
Max extended length La is adjusted by ring 2. FC2 switch is connected with the YELLOW and the GREEN cables. The position of the brass rings along the stainless steel supporting rod is easily adjustable.

WARNING! The electric reed switches can work only if connected to a wiring control circuit in order to activate the electric relay. Do not connect them in series between the power supply and the electric motor!

### 13.5 Encoder GI (linear actuators LMR 01, LMR02 and LMR 03)

Hall effect, bi-directional, incremental encoder
Output configuration: PUSH-PULL
Code GI 21: 2 output channels, 1 pulse per revolution
Code Gl 24: 2 output channels, 4 pulses per revolution
Cable length: as motor cable
Protected against polarity inversion
Protected against any incorrect output connection
NOTE: For conductive cables colour, please refer to the wiring diagram in the "Installation Instructions" supplied with the product.


### 13.6 Encoder EH38 (linear actuators ATL 10, UAL 0, BSA 10, UBA 0)

Bi-directional, incremental, optical encoder
Output configuration: PUSH-PULL
Code EH38: $\quad 2$ output channels, 100 pulses per revolution, with zero set pulse
Cable length: $\quad 1.3 \mathrm{~m}$
Protected against short circuit
Protected against polarity inversion
Protected against any incorrect output connection
Input voltage: $8 \div 24 \mathrm{Vcc}$
No load power consumption:100 mA
Max. commutable current: 50 mA per channel

NOTE: Safety clutch FS cannot be used with rotative encoder (the position reference would be lost due to its slipping).

5 wires cable function


