



#### **OVERALL DIMENSIONS** La = Lc + StrokeStroke Lc 24 31 10 13 Ф Ð ம Ø6+0 Ø 8 +0.1 Ŋ 5 Motor cable length 0.3 m B 2 8 3 Ø 20 (motor with encoder) <u>ر</u> 7 107 Ø4¦4.5 117 Length Stroke ≤ 300 mm Stroke > 300 mm Lc [mm] 90 + Stroke 140 + Stroke

	× +					
STROKE	STROKE	LENGTH				
CODE	[mm]	Lc [mm]	<b>La</b> [mm]	MASS [kg]		
C50	50	140	190	0.85		
C100	100	190	290	1.10		
C150	150	240	390	1.25		
C200	200	290	490	1.40		
C250	250	340	590	1.55		
C300	300	390	690	1.70		

128 + Stroke

### PERFORMANCES AND FEATURES

78 + Stroke

Pull-Push load up to 1 300 N

T [mm]

- Linear speed up to 52 mm/s
- Standard stroke lengths: 50, 100, 150, 200, 250, 300 mm (min. stroke limited by FC switches: 50 mm) (for different / longer stroke lengths please contact us)
- Aluminium housing and rear attachment
- Anodized aluminium push rod tolerance f8
- Aluminium front attachment
- 12, 24 or 36 V DC motor with electromagnetic noise suppressor (motor features details on page 69)
- Duty cycle with max load: 15% over 10 min at (-10 ... +40) °C
- Standard motor mounting position as per dimensional drawing (right-hand, code RH)
- Standard protection IP65
  - Test IP6X according to EN 60529 §12 §13.4-13.6 - Test IPX5 according to EN 60529 §14.2.5 (tests made with not running actuator)
- Long-life lubrication, maintenance free

## ACCESSORIES

- Stainless steel push rod (code SS)
- Two adjustable built-in stroke end switches (code FC2)
- Two adjustable built-in stroke end switches, switching off the motor (code FC2X)
- Extra switch for intermediate position (code FC)
- 2-channels incremental encoder on motor shaft 1 ppr (code GI 21)
  - 4 ppr (code GI 24)

(wiring diagrams on page 75)

Number of pulses	Ratio			
for 100 mm stroke	RN2	RN1	RL2	RL1
GI 21	192	383	483	967
GI 24	767	1 533	1 933	3 867

## **OPTIONS**

- Motor mounting position on opposite side (left-hand, code LH)
- Fixing attachment turned at 90° (code RPT 90)

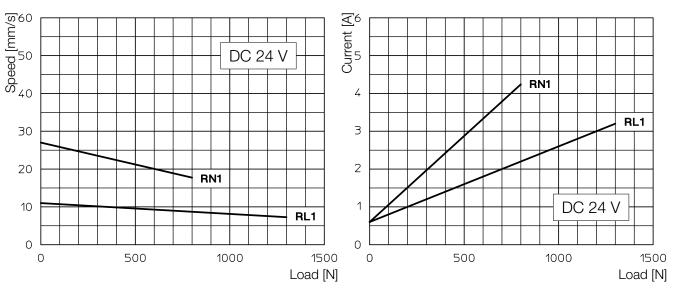


## ACME SCREW LINEAR ACTUATOR

LMR 01

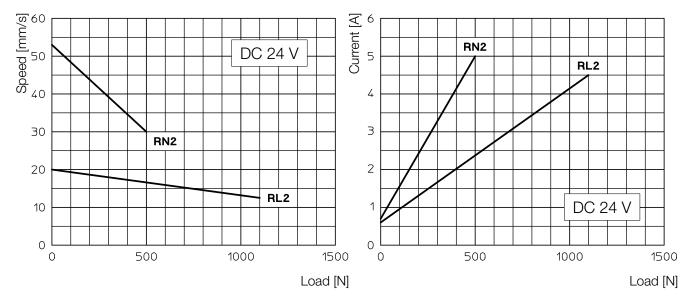
### PERFORMANCES with 24 V DC motor

(Performances with 12 V DC motor: same load, linear speed 10 % less, electrical consumption 2 times more)



1-start acme screw Tr 12×3

### 2-starts acme screw Tr 12×6 (P3)



#### Self-locking conditions

Information about statically self-locking conditions with pull or push load on page 68.

### ORDERING CODE EXAMPLE

LMR 01	RL1	C200	CC 24 V	FC2					
Actuator	Selected ratio	Required stroke	Motor	Stroke end switches	ļ	Accessories		Opt	ions

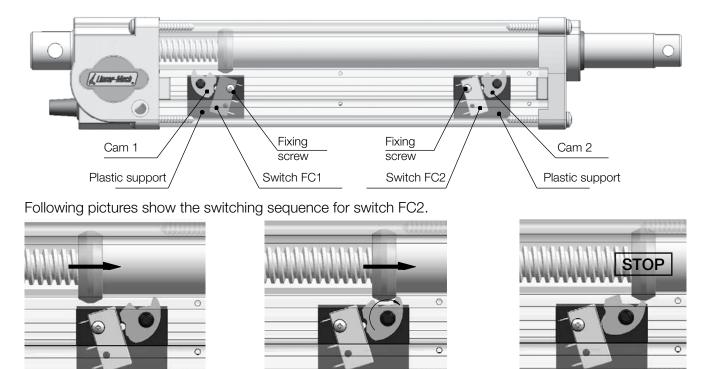


## 13. STROKE END SWITCHES AND POSITIONING CONTROL

## 13.3 Electric stroke end switches FC (linear actuators LMR Series)

Each of the two micro-switches is fitted in a slot with a cam for switches commutation. A screw allows to lock the assembly in the desired position, adjusting in this way the switching position. The nut with suitable shape makes the cams rotate, so to activate the switches. This cam-operated device provides a stable and self-keeping commutation of the switches.

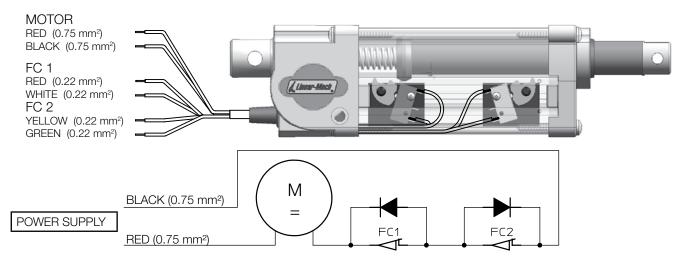
The **MIN. RETRACTED LENGTH Lc** of the actuator is adjusted and controlled by switch FC1. The **MAX. EXTENDED LENGTH La** of the actuator is adjusted and controlled by switch FC2.



Standard switches have silver-plated contacts, max. current 12 A with resistive load - 6 A with inductive load. Switches with gold-plated contacts, very low contact resistance for low working voltage (if connected to PLC or PC), max. current 0.1 A, available on request.

### STANDARD switch connection

Code **FC2**: two electric cam-operated switches, wired on contact NC (to be connected into the external control circuit). On request, the switches can be wired on the contact NO or on switch-over contact CS. Code **FC2X**: two electric cam-operated switches, internally wired between power supply and electric motor, in order to switch off the power supply directly, without relays.





# 13. STROKE END SWITCHES AND POSITIONING CONTROL

## 13.5 Encoder GI (linear actuators LMR 01, LMR02 and LMR 03)

Hall effect, bi-directional, incremental encoder

Output configuration: PUSH-PULL

Code GI 21: 2 output channels, 1 pulse per revolution

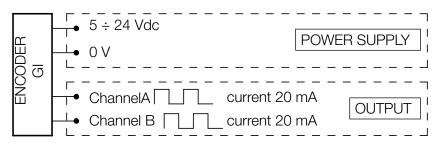
Code GI 24: 2 output channels, 4 pulses per revolution

Cable length: as motor cable

Protected against polarity inversion

Protected against any incorrect output connection

NOTE: For conductive cables colour, please refer to the wiring diagram in the "Installation Instructions" supplied with the product.



## 13.6 Encoder EH38 (linear actuators ATL 10, UAL 0, BSA 10, UBA 0)

Bi-directional, incremental, optical encoder

Output configuration: PUSH-PULL

Code EH38: 2 output channels, 100 pulses per revolution, with zero set pulse

Cable length: 1.3 m

Protected against short circuit

Protected against polarity inversion

Protected against any incorrect output connection

Input voltage: 8÷24 Vcc

No load power consumption:100 mA

Max. commutable current: 50 mA per channel

NOTE: Safety clutch FS cannot be used with rotative encoder (the position reference would be lost due to its slipping).

