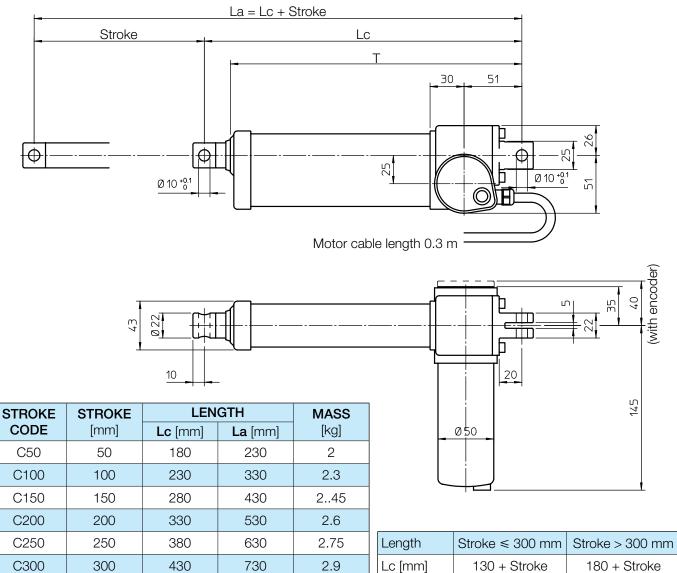


#### **OVERALL DIMENSIONS**



#### PERFORMANCES AND FEATURES

400

Pull-Push load up to 3 000 N

C400

- Linear speed up to 41 mm/s
- Standard stroke lengths:
   50, 100, 150, 200, 250, 300, 400 mm
   (min. stroke limited by FC switches: 50 mm)
   (for different / longer stroke lengths please contact us)

580

980

- Aluminium housing and rear attachment
- Chrome-plated steel push rod
- Stainless steel AISI 303 front attachment
- 12, 24 or 36 V DC motor with electromagnetic noise suppressor (motor features details on page 69)
- Duty cycle with max. load:
   15% over 10 min at (-10 ... +40) °C
- Standard motor mounting position as per dimensional drawing (right-hand, code RH)
- Standard protection IP55
  - Test IP6X according to EN 60529 §12 §13.4-13.6
    Test IPX5 according to EN 60529 §14.2.5 (tests made with not running actuator)
- Long-life lubrication, maintenance free

## ACCESSORIES

3.2

Stainless steel push rod (code SS)

T [mm]

• Two adjustable built-in stroke end switches (code FC2)

107 + Stroke

157 + Stroke

- Two adjustable built-in stroke end switches, switching off the motor (code FC2X)
- Extra switch for intermediate position (code FC))
- 2-channels incremental encoder on motor shaft:
   1 ppr (code GI 21)
  - 4 ppr (code GI 24)

(wiring diagrams on page 75)

Number of pulses	Ratio					
for 100 mm stroke	RN2	RN1	RL2	RL1		
GI 21	246	492	775	1550		
GI 24	984	1968	3100	6200		

### OPTIONS

- Motor mounting position on opposite side (left-hand, code LH)
- Fixing attachment turned at 90° (code RPT 90)

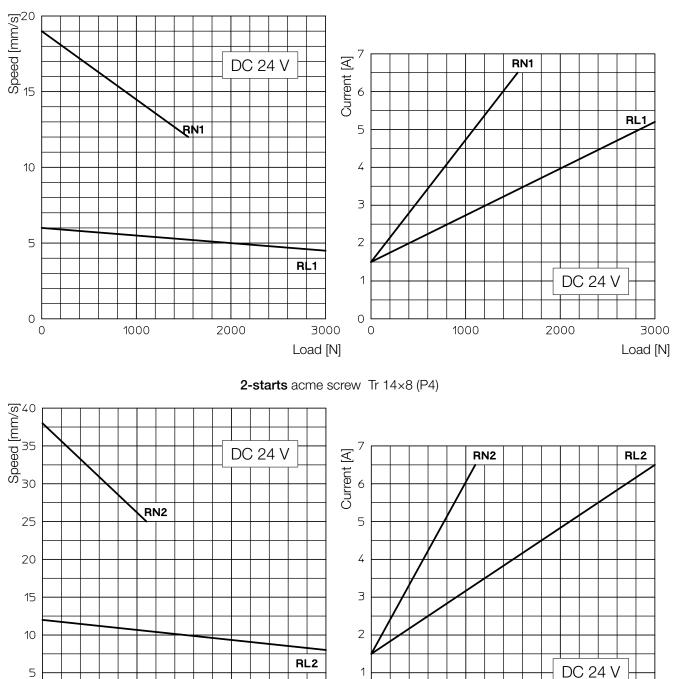


# ACME SCREW LINEAR ACTUATOR

LMR 02

#### PERFORMANCES with 24 V DC motor

(Performances with 12 V DC motor: same load, linear speed 10 % less, electrical consumption 2 times more)



1-start acme screw Tr 14×4

#### Self-locking conditions

5

0

0

Information about statically self-locking conditions with pull or push load on page 68.

2000

#### **ORDERING CODE EXAMPLE**

1000

LMR 02	RL1	C200	CC 24 V	FC2					
Actuator	Selected ratio	Required stroke	Motor	Stroke end switches	/	Accessories		Opt	ions

1

0

0

1000

2000

3000

Load [N]

3000

Load [N]

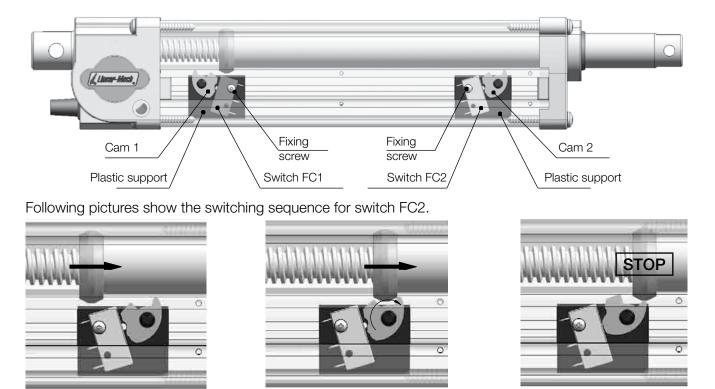


## 13. STROKE END SWITCHES AND POSITIONING CONTROL

## 13.3 Electric stroke end switches FC (linear actuators LMR Series)

Each of the two micro-switches is fitted in a slot with a cam for switches commutation. A screw allows to lock the assembly in the desired position, adjusting in this way the switching position. The nut with suitable shape makes the cams rotate, so to activate the switches. This cam-operated device provides a stable and self-keeping commutation of the switches.

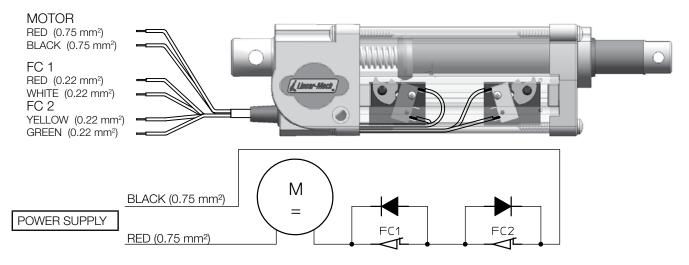
The **MIN. RETRACTED LENGTH Lc** of the actuator is adjusted and controlled by switch FC1. The **MAX. EXTENDED LENGTH La** of the actuator is adjusted and controlled by switch FC2.



Standard switches have silver-plated contacts, max. current 12 A with resistive load - 6 A with inductive load. Switches with gold-plated contacts, very low contact resistance for low working voltage (if connected to PLC or PC), max. current 0.1 A, available on request.

### STANDARD switch connection

Code **FC2**: two electric cam-operated switches, wired on contact NC (to be connected into the external control circuit). On request, the switches can be wired on the contact NO or on switch-over contact CS. Code **FC2X**: two electric cam-operated switches, internally wired between power supply and electric motor, in order to switch off the power supply directly, without relays.





# **13. STROKE END SWITCHES AND POSITIONING CONTROL**

## 13.5 Encoder GI (linear actuators LMR 01, LMR02, LMR 03 and LMP03)

Hall effect, bi-directional, incremental encoder

Output configuration: PUSH-PULL

Code GI 21: 2 output channels, 1 pulse per revolution

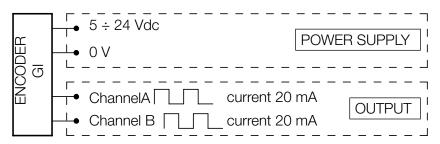
Code GI 24: 2 output channels, 4 pulses per revolution

Cable length: as motor cable

Protected against polarity inversion

Protected against any incorrect output connection

NOTE: For conductive cables colour, please refer to the wiring diagram in the "Installation Instructions" supplied with the product.



## 13.6 Encoder EH38 (linear actuators ATL 10, UAL 0, BSA 10, UBA 0)

Bi-directional, incremental, optical encoder

Output configuration: PUSH-PULL

Code EH38: 2 output channels, 100 pulses per revolution, with zero set pulse

Cable length: 1.3 m

Protected against short circuit

Protected against polarity inversion

Protected against any incorrect output connection

Input voltage: 8÷24 Vcc

No load power consumption:100 mA

Max. commutable current: 50 mA per channel

NOTE: Safety clutch FS cannot be used with rotative encoder (the position reference would be lost due to its slipping).

