OVERALL DIMENSIONS


| STROKE | STROKE | LENGTH |  | MASS |
| :---: | :---: | :---: | :---: | :---: |
| CODE | [mm] | Lc $[\mathrm{mm}]$ | La $[\mathrm{mm}]$ |  |
| C100 | 100 | 230 | 330 | 2.6 |
| C150 | 150 | 280 | 430 | 2.9 |
| C200 | 200 | 330 | 530 | 3.2 |
| C250 | 250 | 380 | 630 | 3.5 |
| C300 | 300 | 430 | 730 | 3.8 |
| C400 | 400 | 580 | 980 | 4.7 |
| C500 | 500 | 680 | 1180 | 5.3 |


| Length | Stroke $\leqslant 300 \mathrm{~mm}$ | Stroke $>300 \mathrm{~mm}$ |
| :--- | :---: | :---: |
| Lc $[\mathrm{mm}]$ | $130+$ Stroke | $180+$ Stroke |
| T $[\mathrm{mm}]$ | $113+$ Stroke | $163+$ Stroke |

## PERFORMANCES AND FEATURES

- Pull-Push load up to 6000 N
- Linear speed up to $25 \mathrm{~mm} / \mathrm{s}$
- Standard stroke lengths: 100, 150, 200, 250, 300, 400, 500 mm (min. stroke limited by FC switches: 50 mm ) (for different / longer stroke lengths please contact us)
- Aluminium housing and rear attachment
- Chrome-plated steel push rod - tolerance f7
- Stainless steel AISI 303 front attachment
- 12, 24 or 36 V DC motor with electromagnetic noise suppressor (motor features details on page 69)
- Duty cycle with max. load: $15 \%$ over 10 min at $(-10 \ldots+40)^{\circ} \mathrm{C}$
- Standard motor mounting position as per dimensional drawing (right-hand, code RH)
- Standard protection IP65
- Test IP6X according to EN 60529 §12 §13.4-13.6
- Test IPX5 according to EN 60529 §14.2.5 (tests made with not running actuator)
- Long-life lubrication, maintenance free


## ACCESSORIES

- Stainless steel push rod (code SS)
- Two adjustable built-in stroke end switches (code FC2)
- Two adjustable built-in stroke end switches, switching off the motor (code FC2X)
- Extra switch for intermediate position (code FC)
- 2-channels incremental encoder on motor shaft 1 ppr (code Gl 21)
4 ppr (code Gl 24)
(wiring diagrams on page 75)

| Number of pulses <br> for 100 mm stroke | Ratio |  |  |  |
| :--- | :---: | :---: | :---: | :---: |
|  | RN2 | RN1 | RL2 | RL1 |
| Gl 21 | 325 | 650 | 862 | 1725 |
| Gl 24 | 1300 | 2600 | 3450 | 6900 |

## OPTIONS

- Motor mounting position on opposite side (left-hand, code LH)
- Fixing attachment turned at $90^{\circ}$ (code RPT 90)

PERFORMANCES with 24 V DC motor
(Performances with 12 V DC motor: same load, linear speed $10 \%$ less, electrical consumption 2 times more)


2-starts acme screw $\operatorname{Tr} 16 \times 8$ (P4)


## Self-locking conditions

Information about statically self-locking conditions with pull or push load on page 68.
ORDERING CODE EXAMPLE

| LMR 03 | RL1 | C200 | CC 24 V | FC2 |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Actuator | Selected <br> ratio | Required <br> stroke | Motor | Stroke end <br> switches | Accessories | Options |  |

## 13. STROKE END SWITCHES AND POSITIONING CONTROL

### 13.3 Electric stroke end switches FC (linear actuators LMR Series)

Each of the two micro-switches is fitted in a slot with a cam for switches commutation.
A screw allows to lock the assembly in the desired position, adjusting in this way the switching position. The nut with suitable shape makes the cams rotate, so to activate the switches.
This cam-operated device provides a stable and self-keeping commutation of the switches.
The MIN. RETRACTED LENGTH Lc of the actuator is adjusted and controlled by switch FC1. The MAX. EXTENDED LENGTH La of the actuator is adjusted and controlled by switch FC2.


Following pictures show the switching sequence for switch FC2.


Standard switches have silver-plated contacts, max. current 12 A with resistive load - 6 A with inductive load. Switches with gold-plated contacts, very low contact resistance for low working voltage (if connected to PLC or PC), max. current 0.1 A , available on request.

## STANDARD switch connection

Code FC2: two electric cam-operated switches, wired on contact NC (to be connected into the external control circuit). On request, the switches can be wired on the contact NO or on switch-over contact CS. Code FC2X: two electric cam-operated switches, internally wired between power supply and electric motor, in order to switch off the power supply directly, without relays.


### 13.5 Encoder GI (linear actuators LMR 01, LMR02 and LMR 03)

Hall effect, bi-directional, incremental encoder
Output configuration: PUSH-PULL
Code GI 21: 2 output channels, 1 pulse per revolution
Code Gl 24: 2 output channels, 4 pulses per revolution
Cable length: as motor cable
Protected against polarity inversion
Protected against any incorrect output connection
NOTE: For conductive cables colour, please refer to the wiring diagram in the "Installation Instructions" supplied with the product.


### 13.6 Encoder EH38 (linear actuators ATL 10, UAL 0, BSA 10, UBA 0)

Bi-directional, incremental, optical encoder
Output configuration: PUSH-PULL
Code EH38: $\quad 2$ output channels, 100 pulses per revolution, with zero set pulse
Cable length: $\quad 1.3 \mathrm{~m}$
Protected against short circuit
Protected against polarity inversion
Protected against any incorrect output connection
Input voltage: $8 \div 24 \mathrm{Vcc}$
No load power consumption:100 mA
Max. commutable current: 50 mA per channel

NOTE: Safety clutch FS cannot be used with rotative encoder (the position reference would be lost due to its slipping).

5 wires cable function


